

Simatic / TI 505 Ethernet Driver

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Simatic / TI 505 Ethernet Driver

Help version 1.043

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Overview

The Simatic / TI 505 Ethernet Driver provides a reliable way to connect Simatic / TI 505 Ethernet devices to OPC client applications; including HMI, SCADA, Historian, MES, ERP, and countless custom applications. It is intended for use in communicating with Simatic 505 Programmable Logic Controllers that may be accessed via either the Siemens Simatic 505-CP2572 Ethernet module, the Siemens 505-CP1434-TCP card, the Control Technology Inc. CTI CP2572 and CTI 2572-A Ethernet cards card, and a CTI 2500 Series CPU module. The driver supports both TCP / IP and UDP transport protocols while using both CAMP and CAMP Packed Task Code messaging protocols for efficient data transfer.

● **Note:** The CTI 2500 Series CPUs are direct replacements for the legacy Simatic TI 500 / 505 CPUs.

Setup

Supported Devices

CTI Interface Cards

CTI 2572, CTI 2572-A, and CP2572 Ethernet interface cards on TI series CPUs TI545, 555, and 565. Simultaneous device connections are allowed. The model should be set to 505-CP2572. For more information, refer to "Connection Limitations" below.

Siemens Interface Cards

505-CP1434-TCP Ethernet host card on TI Series CPUs TI545 and 565. Simultaneous device connections are allowed.

• For more information, refer to the *Siemens 505-CP1434-TCP User Guide*.

CTI 2500 Controller Local Ethernet Port

The CTI 2500 controller's port supports up to three TCP connections (no UDP). Users can connect using the TCP port 4450 or 1505. The model should be set to 505-CP2572.

• **Note:** This affects all CTI 2500 controller models.

Supported Protocols

505: CAMP and CAMP Packed Task Code

IP: UDP and TCP / IP

Device IDs

Up to 2048 devices may be defined on a given channel. Each device on the channel must be uniquely identified by its own IP address.

Connection Limitations

1. The default number of TCP connections allowed for the CTI 2572 / 2752-A and CP2572 cards is 8. When configured from the PLC, this number may be set to a higher or lower number through the Start Network Server command. In the CTI 2572 and CP2572 cards, this can be configured when started from PLC logic. In the CTI 2572-A card, this can be configured when automatically started from EEPROM.
2. DIP Switch 3 in Switch Block 2 enables and disables the Data Share feature. When enabled, the number of TCP server connections is automatically limited to two.
3. To connect to the PLC via the 505-CP1434-TCP card, configure a UDP Server Job in the card.

Channel Properties — General

This server supports the use of simultaneous multiple communications drivers. Each protocol or driver used in a server project is called a channel. A server project may consist of many channels with the same communications driver or with unique communications drivers. A channel acts as the basic building block of an OPC link. This group is used to specify general channel properties, such as the identification attributes and operating mode.

Property Groups	[-] Identification	
General	Name	
Write Optimizations	Description	
Advanced	Driver	
	[-] Diagnostics	
	Diagnostics Capture	Disable

Identification

Name: User-defined identity of this channel. In each server project, each channel name must be unique. Although names can be up to 256 characters, some client applications have a limited display window when browsing the OPC server's tag space. The channel name is part of the OPC browser information.

• For information on reserved characters, refer to "How To... Properly Name a Channel, Device, Tag, and Tag Group" in the server help.

Description: User-defined information about this channel.

• Many of these properties, including Description, have an associated system tag.

Driver: Selected protocol / driver for this channel. This property specifies the device driver that was selected during channel creation. It is a disabled setting in the channel properties.

• **Note:** With the server's online full-time operation, these properties can be changed at any time. This includes changing the channel name to prevent clients from registering data with the server. If a client has already acquired an item from the server before the channel name is changed, the items are unaffected. If, after the channel name has been changed, the client application releases the item and attempts to re-acquire using the old channel name, the item is not accepted. With this in mind, changes to the properties should not be made once a large client application has been developed. Utilize the User Manager to prevent operators from changing properties and restrict access rights to server features.

Diagnostics

Diagnostics Capture: When enabled, this option makes the channel's diagnostic information available to OPC applications. Because the server's diagnostic features require a minimal amount of overhead processing, it is recommended that they be utilized when needed and disabled when not. The default is disabled.

• **Note:** This property is not available if the driver does not support diagnostics.

• For more information, refer to "Communication Diagnostics" in the server help.

Channel Properties — Ethernet Communications

Ethernet Communication can be used to communicate with devices.

Property Groups	[-] Ethernet Settings	
General	Network Adapter	Default
Ethernet Communications		
Write Optimizations		
Advanced		

Ethernet Settings

Network Adapter: Specify the network adapter to bind. When Default is selected, the operating system selects the default adapter.

Channel Properties — Write Optimizations

As with any server, writing data to the device may be the application's most important aspect. The server intends to ensure that the data written from the client application gets to the device on time. Given this goal, the server provides optimization properties that can be used to meet specific needs or improve application responsiveness.

Property Groups	<input type="checkbox"/> Write Optimizations	
General	Optimization Method	Write Only Latest Value for All Tags
Write Optimizations	Duty Cycle	10

Write Optimizations

Optimization Method: controls how write data is passed to the underlying communications driver. The options are:

- **Write All Values for All Tags:** This option forces the server to attempt to write every value to the controller. In this mode, the server continues to gather write requests and add them to the server's internal write queue. The server processes the write queue and attempts to empty it by writing data to the device as quickly as possible. This mode ensures that everything written from the client applications is sent to the target device. This mode should be selected if the write operation order or the write item's content must uniquely be seen at the target device.
- **Write Only Latest Value for Non-Boolean Tags:** Many consecutive writes to the same value can accumulate in the write queue due to the time required to actually send the data to the device. If the server updates a write value that has already been placed in the write queue, far fewer writes are needed to reach the same final output value. In this way, no extra writes accumulate in the server's queue. When the user stops moving the slide switch, the value in the device is at the correct value at virtually the same time. As the mode states, any value that is not a Boolean value is updated in the server's internal write queue and sent to the device at the next possible opportunity. This can greatly improve the application performance.

 - **Note:** This option does not attempt to optimize writes to Boolean values. It allows users to optimize the operation of HMI data without causing problems with Boolean operations, such as a momentary push button.
- **Write Only Latest Value for All Tags:** This option takes the theory behind the second optimization mode and applies it to all tags. It is especially useful if the application only needs to send the latest value to the device. This mode optimizes all writes by updating the tags currently in the write queue before they are sent. This is the default mode.

Duty Cycle: is used to control the ratio of write to read operations. The ratio is always based on one read for every one to ten writes. The duty cycle is set to ten by default, meaning that ten writes occur for each read operation. Although the application is performing a large number of continuous writes, it must be ensured that read data is still given time to process. A setting of one results in one read operation for every write operation. If there are no write operations to perform, reads are processed continuously. This allows optimization for applications with continuous writes versus a more balanced back and forth data flow.

- **Note:** It is recommended that the application be characterized for compatibility with the write optimization enhancements before being used in a production environment.

Channel Properties — Advanced

This group is used to specify advanced channel properties. Not all drivers support all properties; so the Advanced group does not appear for those devices.

Property Groups	<input type="checkbox"/> Non-Normalized Float Handling	
General	Floating-Point Values	Replace with Zero
Write Optimizations	<input type="checkbox"/> Inter-Device Delay	
Advanced	Inter-Device Delay (ms)	0

Non-Normalized Float Handling: A non-normalized value is defined as Infinity, Not-a-Number (NaN), or as a Denormalized Number. The default is Replace with Zero. Drivers that have native float handling may default to Unmodified. Non-normalized float handling allows users to specify how a driver handles non-normalized IEEE-754 floating point data. Descriptions of the options are as follows:

- **Replace with Zero:** This option allows a driver to replace non-normalized IEEE-754 floating point values with zero before being transferred to clients.
- **Unmodified:** This option allows a driver to transfer IEEE-754 denormalized, normalized, non-number, and infinity values to clients without any conversion or changes.

● **Note:** This property is not available if the driver does not support floating point values or if it only supports the option that is displayed. According to the channel's float normalization setting, only real-time driver tags (such as values and arrays) are subject to float normalization. For example, EFM data is not affected by this setting.

● *For more information on the floating point values, refer to "How To ... Work with Non-Normalized Floating Point Values" in the server help.*

Inter-Device Delay: Specify the amount of time the communications channel waits to send new requests to the next device after data is received from the current device on the same channel. Zero (0) disables the delay.

● **Note:** This property is not available for all drivers, models, and dependent settings.

Device Properties — Scan Mode

The Scan Mode specifies the subscribed-client requested scan rate for tags that require device communications. Synchronous and asynchronous device reads and writes are processed as soon as possible; unaffected by the Scan Mode properties.

Property Groups	<input type="checkbox"/> Scan Mode	
General	Scan Mode	Respect Client-Specified Scan Rate ▾
Scan Mode	Initial Updates from Cache	Disable

Scan Mode: specifies how tags in the device are scanned for updates sent to subscribing clients. Descriptions of the options are:

- **Respect Client-Specified Scan Rate:** This mode uses the scan rate requested by the client.
 - **Request Data No Faster than Scan Rate:** This mode specifies the maximum scan rate to be used. The valid range is 10 to 99999990 milliseconds. The default is 1000 milliseconds.
- **Note:** When the server has an active client and items for the device and the scan rate value is

increased, the changes take effect immediately. When the scan rate value is decreased, the changes do not take effect until all client applications have been disconnected.

- **Request All Data at Scan Rate:** This mode forces tags to be scanned at the specified rate for subscribed clients. The valid range is 10 to 99999990 milliseconds. The default is 1000 milliseconds.
- **Do Not Scan, Demand Poll Only:** This mode does not periodically poll tags that belong to the device nor perform a read to get an item's initial value once it becomes active. It is the client's responsibility to poll for updates, either by writing to the `_DemandPoll` tag or by issuing explicit device reads for individual items. *For more information, refer to "Device Demand Poll" in server help.*
- **Respect Tag-Specified Scan Rate:** This mode forces static tags to be scanned at the rate specified in their static configuration tag properties. Dynamic tags are scanned at the client-specified scan rate.

Initial Updates from Cache: When enabled, this option allows the server to provide the first updates for newly activated tag references from stored (cached) data. Cache updates can only be provided when the new item reference shares the same address, scan rate, data type, client access, and scaling properties. A device read is used for the initial update for the first client reference only. The default is disabled; any time a client activates a tag reference the server attempts to read the initial value from the device.

Device Properties — General

A device represents a single target on a communications channel. If the driver supports multiple controllers, users must enter a device ID for each controller.

<p>Property Groups</p> <ul style="list-style-type: none"> General Scan Mode 	<table border="1"> <tr> <td colspan="2">Identification</td> </tr> <tr> <td>Name</td> <td></td> </tr> <tr> <td>Description</td> <td></td> </tr> <tr> <td>Channel Assignment</td> <td></td> </tr> <tr> <td>Driver</td> <td></td> </tr> <tr> <td>Model</td> <td></td> </tr> <tr> <td>ID Format</td> <td>Decimal</td> </tr> <tr> <td>ID</td> <td>2</td> </tr> <tr> <td colspan="2">Operating Mode</td> </tr> <tr> <td>Data Collection</td> <td>Enable</td> </tr> <tr> <td>Simulated</td> <td>No</td> </tr> </table>	Identification		Name		Description		Channel Assignment		Driver		Model		ID Format	Decimal	ID	2	Operating Mode		Data Collection	Enable	Simulated	No
Identification																							
Name																							
Description																							
Channel Assignment																							
Driver																							
Model																							
ID Format	Decimal																						
ID	2																						
Operating Mode																							
Data Collection	Enable																						
Simulated	No																						

Identification

Name: This property specifies the name of the device. It is a logical user-defined name that can be up to 256 characters long, and may be used on multiple channels.

● **Note:** Although descriptive names are generally a good idea, some OPC client applications may have a limited display window when browsing the OPC server's tag space. The device name and channel name become part of the browse tree information as well. Within an OPC client, the combination of channel name and device name would appear as "ChannelName.DeviceName".

● *For more information, refer to "How To... Properly Name a Channel, Device, Tag, and Tag Group" in server help.*

Description: User-defined information about this device.

● Many of these properties, including Description, have an associated system tag.

Channel Assignment: User-defined name of the channel to which this device currently belongs.

Driver: Selected protocol driver for this device. This property specifies the driver selected during channel creation. It is disabled in the channel properties.

Model: This property specifies the specific type of device that is associated with this ID. The contents of the drop-down menu depends on the type of communications driver being used. Models that are not supported by a driver are disabled. If the communications driver supports multiple device models, the model selection can only be changed when there are no client applications connected to the device.

● **Note:** If the communication driver supports multiple models, users should try to match the model selection to the physical device. If the device is not represented in the drop-down menu, select a model that conforms closest to the target device. Some drivers support a model selection called "Open," which allows users to communicate without knowing the specific details of the target device. For more information, refer to the driver help documentation.

ID: This property specifies the device's station / node / identity / address. The type of ID entered depends on the communications driver being used. For many drivers, the ID is a numeric value. Drivers that support a Numeric ID provide users with the option to enter a numeric value whose format can be changed to suit the needs of the application or the characteristics of the selected communications driver. The ID format can be Decimal, Octal, and Hexadecimal. If the driver is Ethernet-based or supports an unconventional station or node name, the device's TCP/IP address may be used as the device ID. TCP/IP addresses consist of four values that are separated by periods, with each value in the range of 0 to 255. Some device IDs are string based. There may be additional properties to configure within the ID field, depending on the driver.

Operating Mode

Data Collection: This property controls the device's active state. Although device communications are enabled by default, this property can be used to disable a physical device. Communications are not attempted when a device is disabled. From a client standpoint, the data is marked as invalid and write operations are not accepted. This property can be changed at any time through this property or the device system tags.

Simulated: This option places the device into Simulation Mode. In this mode, the driver does not attempt to communicate with the physical device, but the server continues to return valid OPC data. Simulated stops physical communications with the device, but allows OPC data to be returned to the OPC client as valid data. While in Simulation Mode, the server treats all device data as reflective: whatever is written to the simulated device is read back and each OPC item is treated individually. The item's memory map is based on the group Update Rate. The data is not saved if the server removes the item (such as when the server is reinitialized). The default is No.

● Notes:

1. This System tag (`_Simulated`) is read only and cannot be written to for runtime protection. The System tag allows this property to be monitored from the client.
2. In Simulation mode, the item's memory map is based on client update rate(s) (Group Update Rate for OPC clients or Scan Rate for native and DDE interfaces). This means that two clients that reference the same item with different update rates return different data.

● Simulation Mode is for test and simulation purposes only. It should never be used in a production environment.

Device Properties — Timing

The device Timing properties allow the driver's response to error conditions to be tailored to fit the application's needs. In many cases, the environment requires changes to these properties for optimum performance. Factors such as electrically generated noise, modem delays, and poor physical connections can influence how many errors or timeouts a communications driver encounters. Timing properties are specific to each configured device.

Property Groups	[-] Communication Timeouts	
General	Connect Timeout (s)	3
Scan Mode	Request Timeout (ms)	5000
Timing	Retry Attempts	3
Auto-Demotion	[-] Timing	
	Inter-Request Delay (ms)	0

Communications Timeouts

Connect Timeout: This property (which is used primarily by Ethernet based drivers) controls the amount of time required to establish a socket connection to a remote device. The device's connection time often takes longer than normal communications requests to that same device. The valid range is 1 to 30 seconds. The default is typically 3 seconds, but can vary depending on the driver's specific nature. If this setting is not supported by the driver, it is disabled.

● **Note:** Due to the nature of UDP connections, the connection timeout setting is not applicable when communicating via UDP.

Request Timeout: This property specifies an interval used by all drivers to determine how long the driver waits for a response from the target device to complete. The valid range is 50 to 9,999,999 milliseconds (167.6667 minutes). The default is usually 1000 milliseconds, but can vary depending on the driver. The default timeout for most serial drivers is based on a baud rate of 9600 baud or better. When using a driver at lower baud rates, increase the timeout to compensate for the increased time required to acquire data.

Attempts Before Timeout: This property specifies how many times the driver issues a communications request before considering the request to have failed and the device to be in error. The valid range is 1 to 10. The default is typically 3, but can vary depending on the driver's specific nature. The number of attempts configured for an application depends largely on the communications environment. This property applies to both connection attempts and request attempts.

Timing

Inter-Request Delay: This property specifies how long the driver waits before sending the next request to the target device. It overrides the normal polling frequency of tags associated with the device, as well as one-time reads and writes. This delay can be useful when dealing with devices with slow turnaround times and in cases where network load is a concern. Configuring a delay for a device affects communications with all other devices on the channel. It is recommended that users separate any device that requires an inter-request delay to a separate channel if possible. Other communications properties (such as communication serialization) can extend this delay. The valid range is 0 to 300,000 milliseconds; however, some drivers may limit the maximum value due to a function of their particular design. The default is 0, which indicates no delay between requests with the target device.

● **Note:** Not all drivers support Inter-Request Delay. This setting does not appear if it is not available.

Device Properties — 505 Protocol

Property Groups	505 Protocol	
General	505 Protocol	CAMP+Packed Task Code
505 Protocol	TI565	No

505 Protocol: This property specifies whether the driver should use CAMP or CAMP+Packed Task Code Protocol when communicating with devices. When set to CAMP, the driver will only use the CAMP Memory Transfer protocol. When set to CAMP+Packed Task Code, the driver will use Packed Task Code when possible in addition to CAMP Memory Transfer. The default value is CAMP+Packed Task Code.

● **Note:** CAMP+Packed Task Mode will be used for C, X, and Y registers when TI565 is enabled.

TI565: This option should be enabled when using a 565 model PLC to access C, X, and Y registers. The default value is disabled. For more information, refer to [Common Data Type Addressing](#).

● **Notes:**

1. Some address types, strings, and arrays are not supported under the Packed Task Code Protocol. For more information, refer to "Packed Task Code Protocol" in [Common Data Type Addressing](#).
2. For best performance when using CAMP+Packed Task Code, the number of task codes per scan on the PLC should be set to the maximum number available, which is typically 8. If using TISOFT, this may be set using Aux Function 19.

CAMP vs. Packed Task Code

For applications where the data can be divided into large blocks, using CAMP memory transfer will result in the most efficient data transfer. Note that, in one CAMP read, up to 125 words could be returned which could include 2000 discrete points. Since CAMP memory transfer allows only one data type and only one memory range per message, applications which read many small blocks or many different data types may benefit from using the Packed Task Code format.

For example, reading 10 V memory values, 10 WY values, 30 WX values and 2 loop process variables would require four messages (one for the V, one for the WY, one for the WX and one for the loop). Using the packed task code format (which allows 14 NITP task code requests to be placed in a single message), allows data to be obtained in a single message.

Optimum Performance Recommendations

All devices on a channel should be set to the same 505 Protocol mode. When possible, the project's data should be divided into the following categories:

1. Items that are capable of utilizing Packed Task Code.
2. Items that are not capable of utilizing Packed Task Code. This includes the following:
 - Arrays
 - Strings

- Address types that are not supported with Packed Task Code.
- Contiguous address ranges > 36 Words. For example, V1, V2, V3, ... V36, V37, V38.

All items in Category 1 should be placed into a device that is set to CAMP+Packed Task Code 505 Protocol mode on a different channel from Category 2 items. It is recommended that the request size be set to 64 or 128.

All items in Category 2 should be placed into a device that is set to CAMP 505 Protocol mode on a different channel from Category 1 items. It is recommended that the Request Size be set to 250.

Note: When reading a project file prior to addition of 505 Protocol option, the default value is set to CAMP.

Device Properties — Addressing Options

Property Groups	<input type="checkbox"/> Addressing Options	
General	Bit Order for Loops/Alarms	Bit 0/1 is LSB
505 Protocol	Bit Order for V, K, WX, WY, and STW	Bit 0/1 is LSB
Addressing Options	0/1-Based Bit Addressing	0-Based

Bit Order for Loops/Alarms

This option is used to select the order in which bits will be presented to Loop and Alarm memory types that are bit-accessible and are being bit-accessed (such as LCF).

MSB=Most Significant Bit

LSB=Least Significant Bit

Note: For the following example, the 1st through 16th bit signifies either 0-15 bits or 1-16 bits depending on if the driver is set at 0-Based bit addressing or 1-Based.

DWord follows the same bit order logic as Words except that there are 32 bits instead of 16.

Bit 0 Is MSB of Word

MSB								LSB							
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16

Bit 1 Is LSB of Word

This is the default setting.

MSB								LSB							
16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1

Note for CTI 2572/2572-A and CP2572: Bit 0/1 Is MSB corresponds to the TICVU I/O server and is not the default setting with this OPC server. Select this option if applicable. Bit 0/1 Is LSB corresponds to the TI Direct I/O server (TIDIR). Select this option to make the OPC server compatible with the TIDIR I/O server. For instance, the TIDIR I/O server should be used as a backup in certain applications.

Bit Order for V, K, WX, WY and STW

This option is used to select the order in which bits will be presented to V, K, WX, WY and STW memory types when bit-accessed.

0/1-Based Bit Addressing

Memory types that allow bit within Word (such as V) can be referenced as a Boolean. The addressing notations for doing this are as follows:

```
<memory type><address>.<bit>
<memory type><address>:<bit>
<memory type><address>,<bit>
```

For each of these syntax, <bit> represents the bit number within the Word or DWord, depending on the memory type. 0/1-Based bit addressing provides two ways of addressing a bit within the given Word or DWord; 0-Based and 1-Based. 0-Based addressing means the first bit begins at 0. With 1-Based, the first bit begins at 1. The bit order for the Word or DWord is irrelevant with this option. In other words, it doesn't matter whether the first bit is the Most Significant Bit or the Least Significant Bit.

● **Note:** In this driver, the first bit will either be bit 0 or bit 1 depending on this 0/1-Based bit addressing setting.

0-Based

This is the default setting.

Data Type	Bit Range
Word	Bits 0-15
DWord	Bits 0-31

1-Based

Data Type	Bit Range
Word	Bits 1-16
DWord	Bits 1-32

● **Note:** 0/1-Based bit addressing does not apply to non-bit addresses such as Word addresses in V memory. These addresses are always 1-Based and are not configurable.

Device Properties — Communications Parameters

Property Groups	<input checked="" type="checkbox"/> Communications Parameters	
General	IP Protocol	UDP
Addressing Options	Port	1505
Communications Parameters	Request Size (bytes)	250

Port Number: This property specifies the port number that the remote device is configured to use. The default port number is 1505.

IP Protocol: This property specifies whether the driver should connect to the remote device using the User Datagram Protocol (UDP) or Transfer Control Protocol (TCP). This driver requires Winsock V1.1 or higher.

● **Note:** If the Simatic 505-CP1434-TCP card is being used, then a UDP server job must also be set up if using

the UDP IP Protocol (or a TCP server job if using the TCP IP Protocol). It is recommended that the TCP IP Protocol have retries set to a greater value than the default setting of 3.

Request Size: This property specifies the number of bytes that may be requested from a device at one time. To refine this driver's performance, configure the request size to one of the following settings: 32, 64, 128, or 250 bytes. The default is 250 bytes.

Device Properties — Redundancy

Property Groups	<input type="checkbox"/> Redundancy	
General	<input type="checkbox"/> Secondary Path ...	
Scan Mode	Operating Mode	Switch On Failure
Timing	Monitor Item	
Redundancy	Monitor Interval (s)	300
	Return to Primary ASAP	Yes

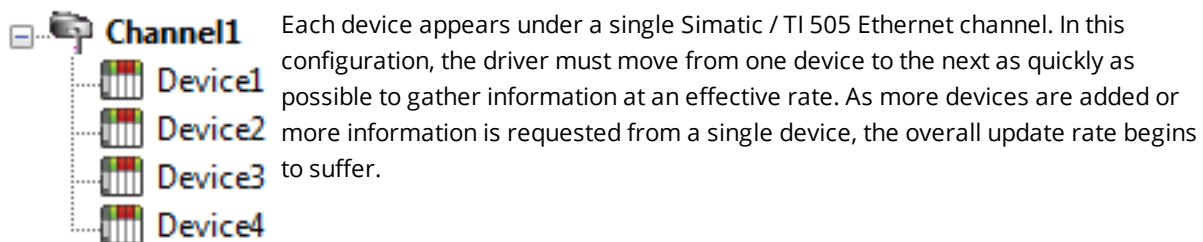
Redundancy is available with the Media-Level Redundancy Plug-In.

• Consult the website, a sales representative, or the user manual for more information.

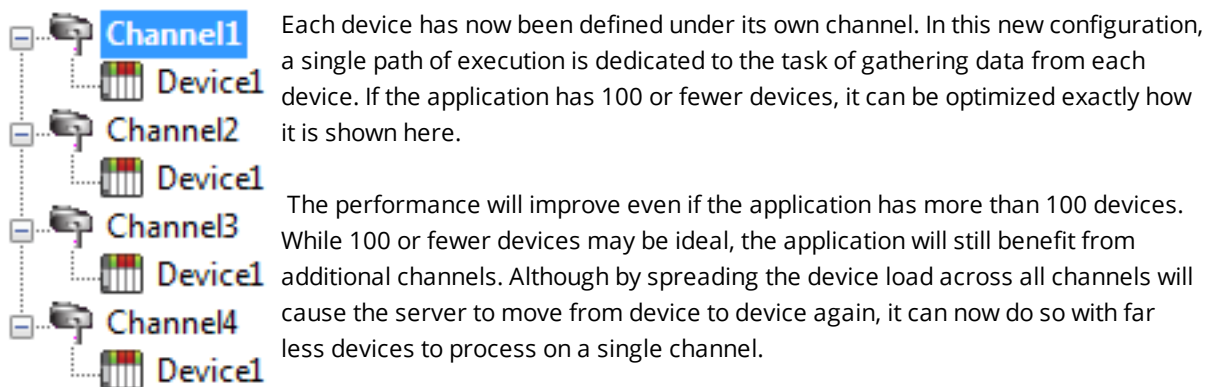
Optimizing Communications

The Simatic / TI 505 Ethernet Driver has been designed to provide the best performance with the least amount of impact on the system's overall performance. While the Simatic / TI 505 Ethernet Driver is fast, there are a couple of guidelines that can be used to control and optimize the application and gain maximum performance.

The server refers to each communications protocol, like Simatic / TI 505 Ethernet, as a channel. Each channel defined in the application represents a separate path of execution in the server. Once a channel has been defined, a series of devices must then be defined under that channel. Each of these devices represents a single Simatic 505 controller from which data will be collected. While this approach to defining the application will provide a high level of performance, it won't take full advantage of the driver or the network. An example of how the application may appear when configured using a single channel is shown below.



If the Simatic / TI 505 Ethernet Driver could only define one single channel, then the example shown above would be the only option available; however, this driver can define up to 100 channels. Using multiple channels distributes the data collection workload by simultaneously issuing multiple requests to the network. An example of how the same application may appear when configured using multiple channels to improve performance is shown below.



Block size, which is available on each defined device, can also affect the Simatic / TI 505 Ethernet Driver performance. Block Size refers to the number of bytes that may be requested from a device at one time. To refine the performance of this driver, configure Block Size to one of the following settings: 32, 64, 128, or 250 bytes. Depending on the Simatic / TI 505 Ethernet device model, the Block Size property can affect the application's performance drastically. A default value of 250 bytes is recommended. If an application has large requests for consecutively ordered data, however, block size should be increased.

Data Types Description

Data Type	Description
Boolean	Single bit
Word	Unsigned 16-bit value bit 0 is the low bit bit 15 is the high bit
Short	Signed 16-bit value bit 0 is the low bit bit 14 is the high bit bit 15 is the sign bit
DWord	Unsigned 32-bit value bit 0 is the low bit bit 31 is the high bit
Long*	Signed 32-bit value bit 0 is the low bit bit 30 is the high bit bit 31 is the sign bit
Float**	32-bit floating point value The driver interprets two consecutive registers as a floating-point value by making the second register the high word and the first register the low word.
String	Null-terminated ASCII string This includes High-Low Low-High byte order selection.

*Long is the same as Double in the TISOFT programming software.

**Float is the same as Real in the TISOFT programming software.

Address Descriptions

Address specifications vary depending on the model in use. Select a link from the following list to obtain specific address information for the model of interest.

[Addressing](#)

[Common Data Type Addressing](#)

[Status Words](#)

Addressing


The following sections define addressing.

[Common Data Type Addressing](#)

[Alarm Addressing](#)


[Loop Addressing](#)

[Find Forced Addressing](#)

 For information on the Event Log, refer the server help documentation.

Common Data Type Addressing

The driver supports the following addresses. The default data type for each address type is indicated in **bold**.

 **Note:** The actual number of addresses available for of each type depends on the PLC's configuration. If the driver finds at runtime that an address is not present in the device, it will post an error message and remove the tag from its scan list.

Address Type	Format	Range	Data Types	Access
Discrete Input*	X<address>	1-65536	Boolean	Read/Write
Discrete Output*	Y<address>	1-65536	Boolean	Read/Write
Word Input	WX<address>	1-65536 1-65535	Short, Word Long, DWord, Float	Read/Write
Word Input Signed Integer	WX<address>S	1-65536 1-65535	Short , Word Long, DWord, Float	Read/Write
Word Input Bit Access	WX<address>.<bit> WX<address>:<bit> WX<address>,<bit>	1-65536 Bit 0/1-15/16 0/1-Based Bit Addressing	Boolean, Short, Word	Read/Write
Word Output	WY<address>	1-65536 1-65535	Short, Word Long, DWord, Float	Read/Write
Word Output Signed Integer	WY<address>S	1-65536 1-65535	Short , Word Long, DWord, Float	Read/Write
Word Output	WY<address>.<bit>	1-65536	Boolean,	Read/Write

Address Type	Format	Range	Data Types	Access
Bit Access	WY<address>:<bit> WY<address>,<bit>	Bit 0/1-15/16 0/1-Based Bit Addressing	Short, Word	
Discrete Control (Internal Coil)*	C<address> CR<address>	1-65536	Boolean	Read/Write
V-Word Memory	V<address>	1-16777215 1-16777214	Short, Word , BCD Long, DWord, Float	Read/Write
V-Word Memory Signed Integer	V<address>S	1-16777215 1-16777214	Short , Word, BCD Long, DWord, Float	Read/Write
V-Word Memory Double Word	V<address>D	1-16777215 1-16777214	Short, Word, BCD Long, DWord , Float	Read/Write
V-Word Memory BCD Decimal	V<address>B	1-16777215 1-16777214	Short, Word, BCD Long, DWord, Float	Read/Write
V-Word Memory Floating Point	V<address>R V<address>P V<address>.	1-16777215 1-16777214	Short, Word, BCD Long, DWord, Float	Read/Write
V-Word Memory Bit Access	V<address>.<bit> V<address>:<bit> V<address>,<bit>	1-16777215 Bit 0/1-15/16 0/1-Based Bit Addressing	Boolean, Short, Word	Read/Write
V-Word Memory As Standard String with HiLo Byte Order***	V<address>.<length>H	V1.2H- V16777215.250H .Bit is string length. Range 2 to 250 bytes.	String	Read/Write
V-Word Memory As Standard String with LoHi Byte Order***	V<address>.<length>L	V1.2H- V16777215.250L .Bit is string length Range 2 to 250 bytes.	String	Read/Write
V-Word Memory As Null-Terminated String with LoHi Byte Order***	V<first>-<last>C <first> is first word <last> is last word	1-16777215 (last-first)=string length Range 1 to 125 words.	String	Read/Write

Address Type	Format	Range	Data Types	Access
V-Word Memory As String with LoHi Byte Order with Length Byte***	V<first>-<last>P <first> is first word <last> is last word	1-16777215 (last - first)=string length Range 1 to 125 words.	String	Read/Write
V-Word Memory As String with LoHi Byte Order Blank-Padded on Right***	V<first>-<last> <first> is first word <last> is last word	1-16777215 (last-first)=string length Range 1 to 125 words.	String	Read/Write
Constant Memory	K<address>	1-16777215 1-16777214	Short, Word , BCD Long, DWord, Float	Read/Write
Constant Memory Signed Integer	K<address>S	1-16777215 1-16777214	Short , Word, BCD Long, DWord, Float	Read/Write
Constant Memory Double Word	K<address>D	1-16777215 1-16777214	Short, Word, BCD Long, DWord , Float	Read/Write
Constant Memory BCD Decimal	K<address>B	1-16777215 1-16777214	Short, Word, BCD Long, DWord, Float	Read/Write
Constant Memory Floating Point	K<address>R K<address>P K<address>.	1-16777215 1-16777214	Short, Word, BCD Long, DWord, Float	Read/Write
Constant Memory Bit Access	K<address>.<bit> K<address>:<bit> K<address>,<bit>	1-16777215 Bit 0/1-15/16 0/1-Based Bit Addressing	Boolean, Short, Word	Read/Write
System Status	STW<address>	1-65536 1-65535	Short, Word Long, DWord, Float	Read/Write
System Status Bit Access	STW<address>.<bit> STW<address>:<bit> STW<address>,<bit>	1-65536 Bit 0/1-15/16 0/1-Based Bit Addressing	Boolean, Short, Word	Read/Write
Timer/Counter Preset	TCP<address>	1-65536 1-65535	Short, Word Long, DWord, Float	Read/Write
Timer/Counter Current	TCC<address>	1-65536 1-65535	Short, Word Long, DWord,	Read/Write

Address Type	Format	Range	Data Types	Access
			Float	
Drum Step Preset	DSP<address>	1-65536 1-65535	Short, Word Long, DWord, Float	Read/Write
Drum Step Current	DSC<address>	1-65536 1-65535	Short, Word Long, DWord, Float	Read/Write
Drum Count Preset**	DCP<drum>.<step> DCP<drum>:<step> DCP<drum>,<step>	drum 1-65536 step 1-16	Short, Word	Read/Write
Drum Current Count	DCC<address>	1-65536 1-65535	Short, Word Long, DWord , Float	Read Only

*X, Y, and C memory types are supported on the 565 model controller by setting the TI565 checkbox in [Communications Properties](#).

**DCP registers must be accessed in groups of 16 words. Therefore, when writing to a DCP register, the driver performs a read to obtain the current values of all 16-word values (DCP00001.01 - DCP00001.16). The driver modifies the one register that is being written to and sends the 16 values to the device. Since the driver performs this read/modify/write procedure, it could be possible for any one of the registers to change between the read and write transaction. The result would be a new value being written over by an older value. It is recommended that users write to another type of memory location (such as Vxxxxx). If using a ladder, transfer the value to a DCP register. When model is set to CTI 2500, the read/modify/write procedure is not used because the driver uses Packed Task Code Protocol to write directly to the DCP drum and step specified by the address.

***For more information, refer to [String Support](#).

Array Support

Non-Boolean addresses accept array notation. To view data as an array, append '[rows][cols]' to an address (e.g., V500 [2][2], V100 [12]).

String Support

Standard String

The Simatic / TI 505 Ethernet Driver supports reading and writing V registers as an ASCII string. When using V registers for string data, each register will contain two bytes of ASCII data. The order of the ASCII data within a given register can be selected when the string is defined. The length of the string can be from 2 to 250 bytes and is entered in place of a bit number. The length must be entered as an even number. The byte order is specified by appending either a "H" or "L" to the address.

Null Terminated

This type of string is a Standard String with LoHi byte order that is null terminated at all times. This means the last byte will always be a null terminator, essentially losing one character place when compared to a Standard String with LoHi byte order.

Length + String

This type of string is also a Standard String with LoHi byte order except the MSB of the first word contains the desired length of the string to follow. This means one character place is lost when compared to a Standard String with LoHi byte order. Based on this length, a string is formed up to the maximum size set by

the address range (such as (<last word> - <first word>) / 2 - 1 bytes). The maximum length of the string can vary between the length byte value and (<last word>-<first word>) / 2 - 1 bytes.

● **Note:** Any null terminators in the string can cut the length short of these maximum lengths. If a string to be written is less than this maximum length, it will be padded on the right with blank-spaces until all maximum bytes contain a non-NULL value.

Blank-Padded on Right

This type of string is a Standard String with LoHi byte order except the string length is always the maximum because the string is padded with blank spaces on the right until its length becomes the maximum (no NULLs). Recall the maximum length of the string is (<last word> - <first word>) / 2 bytes in the address. If a string to be written is less than this maximum length, it too will be padded on the right with blank-spaces until all maximum bytes contain a non-NULL value.

Example 1: Standard String

To address a string starting at V200 with a length of 50 bytes and HiLo byte order, enter V200.50H.

Example 2: Standard String

To address a string starting at V500 with a length of 38 bytes and LoHi byte order, enter V500.38L.

Example 3: Null Terminated

Given:

```
V200/MSB = 'h'
V200/LSB = 'e'
V201/MSB = 'l'
V201/LSB = 'l'
V202/MSB = 'o'
V202/LSB = ' '
V203/MSB = 'w'
V203/LSB = 'o'
V204/MSB = 'r'
V204/LSB = 'l'
V205/MSB = 'd'
```

To address a null-terminated string starting at V200 with a length of 10 bytes and the memory data is as stated above:

V200-204C would read "hello wor".

● **Note:** Only 9 characters can be displayed because the last is the null terminator.

Example 4: Length Byte + String

Given:

```
V200/MSB = 0x04
V200/LSB = 'e'
V201/MSB = 'l'
V201/LSB = 'l'
V202/MSB = 'o'
V202/LSB = ' '
V203/MSB = 'w'
V203/LSB = 'o'
V204/MSB = 'r'
V204/LSB = 'l'
V205/MSB = 'd'
```

To address a string with length byte information, starting at V200 and the memory data is as stated above: V200-204P would read "ello".

● **Note:** The length byte is 0x04 so only 4 characters are displayed. If the length byte were 0x07, V200-204P would read "ello wo".

Example 5: Blank-Padded on Right

Given:

V200/MSB = 'h'
 V200/LSB = 'e'
 V201/MSB = 'l'
 V201/LSB = 'l'
 V202/MSB = 'o'
 V202/LSB = NULL
 V203/MSB = 'w'
 V203/LSB = 'o'
 V204/MSB = 'r'
 V204/LSB = 'l'
 V205/MSB = 'd'

To address a blank padded string starting at V200 with a length of 10 bytes and the memory data is as stated above:

V200-204 would read "hello".

● **Note:** All 10 characters are displayed with the null-terminated string "hello" padded with 5 spaces to fill the 5 words.

To write "world" to this address, the memory data would look as follows:

V200/MSB = 'w'
 V200/LSB = 'o'
 V201/MSB = 'r'
 V201/LSB = 'l'
 V202/MSB = 'd'
 V202/LSB = ' '
 V203/MSB = ' '
 V203/LSB = ' '
 V204/MSB = ' '
 V204/LSB = ' '
 V205/MSB = ' '

Since "world" is less than 10 characters in length, it is padded with blanks to become 10 characters in length.

Packed Task Code Protocol

The following address types, strings, and arrays are not supported under Packed Task Code Protocol. To increase efficiency, CAMP Protocol will be used instead.

Drum Count Preset (DCP)

Discrete Input (X)

Discrete Output (Y)

Discrete Control (C or CR)

Addresses greater than '30720' for Drum Step Preset (DSP) and Drum Step Current (DSC)

Notes:

1. Packed Task Code Protocol will be used for writing address types X, Y, and C.
2. If the TI565 option is selected in Communications Properties, Packed Task Code Protocol will be used for reading and writing the X, Y, and C address types independent of the 505 Protocol property.
3. Task Codes TC7F (Read Block) and TC5A (Write Block) are used.
4. When model is set to CTI 2500, the Packed Task Code protocol is used for reads and writes of DCP registers. This enables driver to support all firmware versions running in CTI 2500 series controllers.

Status Words

For all Status Words, Bit 1 is the Most Significant Bit (MSB) and Bit 16 is the Least Significant Bit (LSB) in order from left to right. Users can configure bit addressing to be 0-15 or 1-16 addressing, and can also set the driver to use 1 or 15 as the MSB (changing the bit referencing). For more information, refer to [Addressing Options](#).

Note: Only addresses that are not used by the controller can be written.

Register	Description	CP525	CP545	CP565	CTI 2500
STW00001	Non-Fatal errors Bit 4, 1 = Password been entered Bit 5, 1 = Password been entered and disabled Bit 6, 1 = User program error* Bit 7, 1 = Subroutine stack overflow Bit 8, 1 = Time of day clock failure Bit 10 = Special function module communication error Bit 11, 1 = Previous RLL instruction failed Bit 12, 1 = I/O module failure or I/O module configuration mismatch Bit 13, 1 = Communication port failure Bit 14, 1 = Scan overrun Bit 15, 1 = Battery low	x	x	x	x
STW00002	Base Control Status. Each bit reflects the status of a single base. 0 = Status is good. 1 = Base is not present or has a problem. Bit 1, Base 15 Bit 2, Base 14 Bit 3, Base 13 Bit 4, Base 12 Bit 5, Base 11 Bit 6, Base 10 Bit 7, Base 9	x	x	x	x

Register	Description	CP525	CP545	CP565	CTI 2500
	Bit 8, Base 8 Bit 9, Base 7 Bit 10, Base 6 Bit 11, Base 5 Bit 12, Base 4 Bit 13, Base 3 Bit 14, Base 2 Bit 15, Base 1 Bit 16, Base 0				
STW00003-00009	Profibus DP Slave Status Each bit is 0 if a slave is present, or 1 if the slave is missing or failed. STW03 Bit 1-16 slave addresses 16-1 STW04 Bit 1-16 slave addresses 32-17 STW05 Bit 1-16 slave addresses 48-33 STW06 Bit 1-16 slave addresses 64-49 STW07 Bit 1-16 slave addresses 80-65 STW08 Bit 1-16 slave addresses 96-81 STW09 Bit 1-16 slave addresses 112-97	x	x	x	x
STW00010	Contains the value of the previous dynamic scan time.	x	x	x	x
STW00011	Indicates the status of the modules in the Local Base (Base 0). Each bit indicates a module in a slot. 0 = Good 1 = Module not present or failed Bit 1 - 16 = Module 16 - 1	x	x	x	x
STW00012-00026	Status bits for modules in bases 1 - 15, STW012 = Base 1... Bit range is the same as for STW011.	x	x	x	x
STW00027-00138	This range of Status Words apply to the Profibus DP slave channels if present. STW027 is slave 1...STW138 is slave 112. Bit range is the same as for STW011.	x	x	x	x
STW00139	This Status Word provides a count of the discrete points (X/Y or C) that are currently forced.	x	x	x	x
STW00140	This Status Word provides a count of the word points (WX/WY) that are currently forced.	x	x	x	x
STW00141-00144	Date, Time, and Day of Week	N/A	N/A	N/A	N/A
STW141	Bit 1-4, Year tens digit Bit 5-8, Year units digit Bit 9-12, Month tens digit Bits 13-16, Month units	x	x	x	x

Register	Description	CP525	CP545	CP565	CTI 2500
STW142	Bit 1-4, Day - Tens digit Bit 5-8, Day - Units digit Bit 9-12, Hour - Tens digit Bit 13-16, Hour - Units digit	x	x	x	x
STW143	Bit 1-4, Minute - Tens digit Bit 5-8, Minute - Units digit Bit 9-12, Seconds - Tens digit Bit 13-16, Seconds - Units digit	x	x	x	x
STW144	Bit 1-4, Seconds - Tenths digit Bit 5-8, Seconds - Hundredths digit Bit 9-12, Not used - Always 0 Bit 13-16, Day of the week	x	x	x	x
STW00145	Receive Error Counts	x	x	x	x
STW00146	Timeout Counts	x	x	x	x
STW00147	This Status Word records the number of times that the Profibus-DP slaves have failed to respond to a request from the Series 505 or CTI 2500 CPU since the most recent restart.	x	x	x	x
STW00148	This Status Word records the number of times that the Profibus-DP I/O channel has experienced a loss of token since the most recent restart.	x	x	x	x
STW00149-00160	Reserved	N/A	N/A	N/A	N/A
STW00161	Special Function Processor Fatal Error Bit 1, 1 = ROM error Bit 2, 1 = RAM error Bit 3, 1 = Operating system error Bit 4, 1 = Invalid control block encountered Bit 5, 1 = Diagnostic failure Bit 7, 1 = S Memory is inconsistent Bit 8 = Special function program received from RLL is invalid	x	x	x	x
STW00162	Special Function Processor Non-Fatal Errors Bit 1, 1 = Port 1 communication error** Bit 3, 1 = Port overrun error Bit 4, 1 = Analog alarm overrun error Bit 5, 1 = Cyclic special function programs overrun error Bit 6, 1 = Normal special function program queue is full Bit 7, 1 = Priority special function program queue is full Bit 8, 1 = Cyclic special function program queue is full Bit 9, 1 = Loop calculation error Bit 10, 1 = Analog alarm calculation error Bit 11, 1 = Control block disabled Bit 12, 1 = Attempt to execute undefined special function	x	x	x	x

Register	Description	CP525	CP545	CP565	CTI 2500
	program or subroutine Bit 13, 1 = Attempt to invoke restricted special function program or subroutine				
STW00163	Contains the number of the ladder subroutine that caused the stack overflow	x	x	x	x
STW00164-00165	Contains the source RLL checksum (32 Bit integer)	x	x	x	x
STW00166-00167	Contains the compiled RLL checksum (32 Bit integer)	x	x	x	x
STW00168	Dual RBC Status Bit 1-16 are bases 15-0 For each Bit: 0 = Dual RBC present and good 1 = Error or single RBC	x	x	x	x
STW00169-00175	Not used	x	x	x	x
STW00176	Dual Power Supply Status Bit 1-16 are bases 15-0 For each Bit: 0 = Dual power supply present and good 1 = Error or single power supply	x	x	x	x
STW00177-00183	Not used	x	x	x	x
STW00184	Module Mismatch Indicator Bit 1, 1 = Module mismatch error Bit 5-8 = Indicates the number of the base with the error	x	x	x	x
STW00185-00190	Not used	x	x	x	x
STW00191	Serial Port Print Status	N/A	N/A	N/A	x
STW00192	Discrete Execution Scan Time - The time spent on the last scan	x	x	x	x
STW00193-199	Not used	x	x	x	x
STW00200	User Program Error Cause (associated with Bit 6 of STW001). Codes are as follows: 0 = No error 1 = Reference to an application that is not installed*** 2 = Attempted to unlock a flag that is not held by an application*** 3 = Mismatched lock/unlock instructions*** 4 = Subroutine nesting level exceeded	x	x	x	x

Register	Description	CP525	CP545	CP565	CTI 2500
	5 = Table overflow 6 = Attempted to call a non-existent subroutine 7 = VMEbus access failed due to a bus error*** 8 = Special function program has not been compiled or does not exist 9 = Special function program has been disabled 10 = Special function program type is restricted or cyclic 11 = Special function program or subroutine is being edited 12 = Special function program or subroutine is being executed by an interrupt task 13 = User-scheduled fast loop is not configured 14 = User-scheduled fast loop is disabled				
STW00201	First Scan Flags Bit 1, 1 = First Run Mode scan or single scan after compile Bit 2, 1 = First Run Mode scan or single scan after Program Mode Bit 3, 1 = First Run Mode scan after transition from Hold Mode Bit 9, 1 = First scan after battery bad power-up restart Bit 10, 1 = First scan after battery good power-up restart Bit 11, 1 = First scan after compile restart Bit 12, 1 = First scan after partial restart	x	x	x	x
STW00202-00205	Not used	x	x	x	x
STW00206-00207	U-Memory checksum C0 (32-bit integer)	x	x	x	N/A
STW00208-00209	U-Memory Checksum C1 (32 bit integer)	x	x	x	N/A
STW00210	Base Poll Enable Flags Bit 1-16 are bases 15-0 For each Bit: 0 = Base cannot be polled 1 = Base can be polled	x	x	x	x
STW00211-00217	Profibus Poll Enable Flags Each bit is 1 if the slave is defined and enabled. STW211 Bit 1-16 slave addresses 16-1 STW212 Bit 1-16 slave addresses 32-17 STW213 Bit 1-16 slave addresses 48-33 STW214 Bit 1-16 slave addresses 64-49 STW215 Bit 1-16 slave addresses 80-65 STW216 Bit 1-16 slave addresses 96-81 STW217 Bit 1-16 slave addresses 112-97	x	x	x	x

Register	Description	CP525	CP545	CP565	CTI 2500
STW00218	Not used	x	x	x	x
STW00219	RLL Task Overrun Bit 1, Task 1: 0 = Good, 1 = Task scan cycle overrun Bit 2, Task 2: 0 = Good, 1 = Task scan cycle overrun	x	x	x	N/A
STW00220	Interrupting Slots in Local Base Bit 1-16 are slots 16-1 For each Bit: 1 = Interrupt request active at module located in this slot	x	x	N/A	N/A
STW00221	Module Interrupt Request Count	x	x	N/A	N/A
STW00222	Spurious Interrupt Count	N/A	N/A	x	N/A
STW00223-00224	Binary Time of Day (32 bit integer)	x	x	x	x
STW00225	Binary Relative Day (with 1/1/1984 being day 0)	x	x	x	x
STW00226	Time of Day Status Bit 1, 1 = Current time is prior to time reported in the last task 1 RLL scan Bit 2-9, Reserved Bit 10, 1 = Time is valid Bit 11, 1 = Time synchronization is over a network Bit 12-13, Time Resolution 00 = .001 second 01 = .01 second 02 = .1 second 03 = 1 second Bit 14, 1 = Time synchronization error Bit 15, 1 = No time synchronization input for the time transmitter	x	x	x	x
STW00227-00228	Bus Error Access Address	N/A	N/A	x	N/A
STW00229-00230	Bus Error Program Offset	N/A	N/A	x	N/A
STW0231	Profibus DP I/O Status Bit 1, 1 = DP in operate state Bit 2, 1 = DP in clear state Bit 3, 1 = Error: Unable to download configuration to the Profibus interface Bit 4, 1 = Error: Unable to retrieve slave diagnostics from the interface Bit 5, 1 = DP bus error Bit 16, 1 = DP I/O bus system is not configured	x	x	x	x
STW00232-	Profibus I/O Diagnostics Status	x	x	x	x

Register	Description	CP525	CP545	CP565	CTI 2500
00238	Each bit is 1 if the slave signals a diagnostic that has not been read by an RSD RLL instruction. STW232 Bit 1-16 slave addresses 16-1 STW233 Bit 1-16 slave addresses 32-17 STW234 Bit 1-16 slave addresses 48-33 STW235 Bit 1-16 slave addresses 64-49 STW236 Bit 1-16 slave addresses 80-65 STW237 Bit 1-16 slave addresses 96-81 STW238 Bit 1-16 slave addresses 112-97				
STW00239-00240	Source Special Function Program/Subroutine Checksum	x	x	x	x
STW00241-00242	Compiled Special Function Program/Subroutine Checksum	x	x	x	x
STW00243	Reserved	N/A	N/A	N/A	x
STW00244	Additional Control Status Flags Bit 1, Controller Mode 0 = Program Mode, 1 = Run Mode Bit 2, Scan Mode 0 = Variable, 1 = Fixed Bit 3, User Program Source 0 = Ram, 1 = Flash Bit 4, Ethernet Port Link Status 1 = Connected Bit 5, TCP/IP Network Status 1 = Operational Bit 6, Duplicate IP Address Status 1 = Duplicate Detected	N/A	N/A	N/A	x
STW00245	Additional Controller Error Status Bit 1, 1 = Fatal error present Bit 2, Reserved Bit 3, 1 = One or more remote bases are not communicating	N/A	N/A	N/A	x
STW00246	Fatal Error Code. This contains the fatal error code when a fatal error is present.	N/A	N/A	N/A	x
STW00247-00257	CTI Support Diagnostics	N/A	N/A	N/A	x
STW00259	Product Serial Number	N/A	N/A	N/A	x
STW00260	Firmware Major Release Number	N/A	N/A	N/A	x
STW00261	Firmware Minor Release Number	N/A	N/A	N/A	x
STW00262-00298	CTI Support Diagnostics	N/A	N/A	N/A	x
STW00299	Peak Scan Time	N/A	N/A	N/A	x
STW00300-454	CTI Support Statistics	N/A	N/A	N/A	x
STW00455-00469	Remote Base Receive Errors. This contains the number of times that the controller encountered an error reading the response message from the remote base.	N/A	N/A	N/A	x

Register	Description	CP525	CP545	CP565	CTI 2500
	STW 455 corresponds to remote base 1. STW 456 – STW 469 correspond to remote bases 2 – 15.				
STW00470	Not used	N/A	N/A	N/A	x
STW00471-00485	Abnormal Logoff Count – Remote Base 1 - 15. This contains the number of times that the controller stopped communicating with the remote base due to communications errors or response timeouts. STW 471 corresponds to remote base 1. STW 472 – STW 485 correspond to remote bases 2 – 15.	N/A	N/A	N/A	x
STW00486	Not used	N/A	N/A	N/A	x
STW00487-00501	Timeout Count – Remote Base 1 – 15. This contains the number of times that the base failed to respond to a request from the controller within the specified time. STW 487 corresponds to remote base 1. STW 488 – STW 501 correspond to remote bases 2 – 15.	N/A	N/A	N/A	x

*For more information, refer to the register "STW200".

**Not used by the CTI 2500.

***This is only for CP575.

Alarm Addressing

The driver supports the following addresses. The default data type for each address type is indicated in **bold**.

● **Note:** The actual number of addresses available for of each type depends on the PLC's configuration. If the driver finds at runtime that an address is not present in the device, it will post an error message and remove the tag from its scan list.

Address Type	Format	Range	Data Types	Access
Alarm Status (V) Flags	AVF<address>	1-65536	Word	Read/Write
Alarm Status (V) Flag Bit Access*	AVF<address>.<bit> AVF<address>:<bit> AVF<address>,<bit>	1-65536 Bit 0/1-15/16 0/1-Based Bit Addressing	Boolean, Word	Read/Write
Alarm Control (C)Flags	ACF<address>	1-65535	DWord	Read/Write
Alarm Control (C) Flag Bit Access**	ACF<address>.<bit> ACF<address>:<bit> ACF<address>,<bit>	1-65535 Bit 0/1-31/32 0/1-Based Bit Addressing	Boolean, DWord	Read/Write
Alarm PV High Alarm	APVH<address>	1-65535	Float	Read/Write

Address Type	Format	Range	Data Types	Access
Alarm PV Low Alarm	APVL<address>	1-65535	Float	Read/Write
Alarm Process Variable	APV<address>	1-65535	Float	Read/Write
Alarm High Limit	AHA<address>	1-65535	Float	Read/Write
Alarm Low Limit	ALA<address>	1-65535	Float	Read/Write
Alarm Orange Deviation Alarm	AODA<address>	1-65535	Float	Read/Write
Alarm Yellow Deviation Alarm	AYDA<address>	1-65535	Float	Read/Write
Alarm Sample Rate	ATS<address>	1-65535	Float	Read/Write
Alarm Setpoint	ASP<address>	1-65535	Float	Read/Write
Alarm Error	AERR<address>	1-65535	Float	Read Only
Alarm High High Alarm Limit	AHHA<address>	1-65535	Float	Read/Write
Alarm Low Low Alarm Limit	ALLA<address>	1-65535	Float	Read/Write
Alarm Rate of Change Alarm	ARCA<address>	1-65535	Float	Read/Write
Alarm Setpoint High Limit	ASPH<address>	1-65535	Float	Read/Write
Alarm Setpoint Low Limit	ASPL<address>	1-65535	Float	Read/Write
Alarm Alarm Deadband	AADB<address>	1-65535	Float	Read/Write
Alarm Raw High Alarm Limit	AHAR<address>	1-65536	Word	Read/Write
Alarm Raw Low Alarm Limit	ALAR<address>	1-65536	Word	Read/Write
Alarm Raw Process Variable	APVR<address>	1-65536	Word	Read/Write
Alarm Raw Orange Deviation	AODAR<address>	1-65536	Word	Read/Write
Alarm Raw Yellow Deviation	AYDAR<address>	1-65536	Word	Read/Write
Alarm Raw Setpoint	ASPR<address>	1-65536	Word	Read/Write
Alarm Raw Alarm Deadband	ADBR<address>	1-65536	Word	Read/Write
Alarm Raw Error	AERRR<address>	1-65536	Word	Read Only
Alarm Raw High-High Alarm Limit	AHHAR<address>	1-65536	Word	Read/Write
Alarm Raw Low-Low Alarm Limit	ALLAR<address>	1-65536	Word	Read/Write
Alarm Raw Setpoint Low Limit	ASPLR<address>	1-65536	Word	Read/Write
Alarm Raw Setpoint High Limit	ASPHR<address>	1-65536	Word	Read/Write

Address Type	Format	Range	Data Types	Access
Alarm MSW Alarm C Flags	ACFH<address>	1-65536	Word	Read/Write
Alarm LSW Alarm C Flags	ACFL<address>	1-65536	Word	Read/Write
Alarm ACK Flag	AACK<address>	1-65536	Word	Read Only

*For more information, refer to [AVF Bit Definitions](#).

**For more information, refer to [ACF Bit Definitions](#).

Array Support

Non-Boolean addresses accept array notation. To view data as an array, append '[rows][cols]' to an address. For example, V500 [2][2], V100 [12].

Packed Task Code Protocol

The following address types and arrays are not supported under Packed Task Code Protocol. CAMP Protocol will be used instead.

- Alarm Control (C) Flags (ACF)
- Alarm Raw High Alarm Limit (AHAR)
- Alarm Raw Low Alarm Limit (ALAR)
- Alarm Raw Process Variable (APVR)
- Alarm Raw Orange Deviation (AODAR)
- Alarm Raw Yellow Deviation (AYDAR)
- Alarm Raw Setpoint (ASPR)
- Alarm Raw Alarm Deadband (ADBR)
- Alarm Raw Error (AERRR)
- Alarm Raw High-High Alarm Limit (AHHAR)
- Alarm Raw Low-Low Alarm Limit (ALLAR)
- Alarm Raw Setpoint Low Limit (ASPLR)
- Alarm Raw Setpoint High Limit (ASPHR)

AVF Bit Definitions

Analog Alarm Variable Flag Data Element Format

The server default settings are shown in **bold**.

MSB		LSB	
ABCD	EFGH	IJKL	MNOP

The AVF bit has the following format.

V/W, **X**/Y

V=0-based bit addressing. Bit 0 is MSB.

W=1-based bit addressing. Bit 1 is MSB (Simatic 505 documentation).

X=0-based bit addressing. Bit 0 is LSB.

Y=1-based bit addressing. Bit 1 is LSB.

Element	AVF Bit	Description
A	0/1, 15/16	1=Enable alarm*
B	1/2, 14/15	1=Disable alarm*
C	2/3, 13/14	1=PV is in high-high alarm
D	3/4, 12/13	1=PV is in high alarm
E	4/5, 11/12	1=PV is in low alarm
F	5/6, 10/11	1=PV is in low-low alarm
G	6/7, 9/10	1=PV is in yellow deviation alarm
H	7/8, 8/9	1=PV is in orange deviation alarm
I	8/9, 7/8	1=PV is in rate of change alarm
J	9/10, 6/7	1=Broken transmitter alarm
K	10/11, 5/6	1=Analog alarm is overrunning
L	11/12, 4/5	1=Alarm is enabled**
M	12/13, 3/4	Not used, set to 0
N	13/14, 2/3	Not used, set to 0
O	14/15, 1/2	Not used, set to 0
P	15/16, 0/1	Not used, set to 0

*Elements A and B are write-only triggers. Writing 1 to the triggers sets the mode. The mode (or status) is reported in Element L (Bit 12).

**If a word is selected for the analog alarm V-flags, element L is written as bit 12 is written. If a C or Y is selected, bit 12 (element L) is not used.

Note: If an analog alarm is programmed and not disabled, the controller will begin to monitor the programmed variables as soon as the controller is placed in RUN mode.

ACF Bit Definitions

Analog Alarm Control Flag Data Element Format

The server default settings are shown in **bold**.

MSB				LSB			
ABCD	EFGH	IJKL	MNOP	QRST	UVWX	YZab	cdef

The ACF bit has the following format:

V/W, X/Y

V=0-based bit addressing. Bit 0 is MSB.

W=1-based bit addressing. Bit 1 is MSB (Simatic 505 documentation).

X=0-based bit addressing. Bit 0 is LSB.

Y=1-based bit addressing. Bit 1 is LSB.

Element	ACF bit	Description
A	0/1, 31/32	0=PV scale 0% offset 1=PV scale 20% offset
B	1/2, 30/31	1=Take square root of PV

Element	ACF bit	Description
C	2/3, 29/30	1=Monitor HIGH/LOW alarms
D	3/4, 28/29	1=Monitor HIGH-HIGH/LOW-LOW alarms
E	4/5, 27/28	1=Monitor yellow/orange deviation alarm
F	5/6, 26/27	1=Monitor rate-of-change alarm
G	6/7, 25/26	1=Monitor broken transmitter alarm
H	7/8, 24/25	0=Local setpoint 1=Remote setpoint
I	8/9, 23/24	Unused, set to 0
J	9/10, 22/23	Unused, set to 0
K	10/11, 21/22	Unused, set to 0
L	11/12, 20/21	Unused, set to 0
M	12/13, 19/20	Unused, set to 0
N	13/14, 18/19	Unused, set to 0
O	14/15, 17/18	Unused, set to 0
P	15/16, 16/17	Unused, set to 0
Q	16/17, 15/16	Unused, set to 0
R	17/18, 14/15	Unused, set to 0
S	18/19, 13/14	Unused, set to 0
T	19/20, 12/13	Unused, set to 0
U	20/21, 11/12	0=Process variable is unipolar 1=Process variable is bipolar
V	21/22, 10/11	Unused, set to 0
W	22/23, 9/10	Contains SF program number (if an SF program is scheduled to be called)
X	23/24, 8/9	Contains SF program number (if an SF program is scheduled to be called)
Y	24/25, 7/8	Contains SF program number (if an SF program is scheduled to be called)
Z	25/26, 6/7	Contains SF program number (if an SF program is scheduled to be called)
a	26/27, 5/6	Contains SF program number (if an SF program is scheduled to be called)
b	27/28, 4/5	Contains SF program number (if an SF program is scheduled to be called)
c	28/29, 3/4	Contains SF program number (if an SF program is scheduled to be called)
d	29/30, 2/3	Contains SF program number (if an SF program is scheduled to be called)
e	30/31, 1/2	Contains SF program number (if an SF program is scheduled to be called)

Element	ACF bit	Description
f	31/32, 0/1	Contains SF program number (if an SF program is scheduled to be called)

Loop Addressing

The driver supports the following addresses. The default data type for each address type is indicated in **bold**.

● **Note:** The actual number of addresses available for of each type depends on the PLC's configuration. If the driver finds at runtime that an address is not present in the device, it will post an error message and remove the tag from its scan list.

Address Type	Format	Range	Data Types	Access
Loop Gain	LKC<address>	1-65535	Float	Read/Write
Loop Reset Time (min.)	LTI<address>	1-65535	Float	Read/Write
Loop Rate Time (min.)	LTD<address>	1-65535	Float	Read/Write
Loop High Alarm Limit	LHA<address>	1-65535	Float	Read/Write
Loop Low Alarm Limit	LLA<address>	1-65535	Float	Read/Write
Loop Process Variable	LPV<address>	1-65535	Float	Read/Write
Loop PV High Limit	LPVH<address>	1-65535	Float	Read/Write
Loop PV Low Limit	LPVL<address>	1-65535	Float	Read/Write
Loop Orange Dev Alarm Limit	LODA<address>	1-65535	Float	Read/Write
Loop Yellow Dev Alarm Limit	LYDA<address>	1-65535	Float	Read/Write
Loop Sample Rate	LTS<address>	1-65535	Float	Read/Write
Loop Setpoint	LSP<address>	1-65535	Float	Read/Write
Loop Output (%)	LMN<address>	1-65535	Float	Read/Write
Loop Status (V) Flags	LVF<address>	1-65536	Word	Read/Write
Loop Status (V) Flag Bit Access*	LVF<address>.<bit> LVF<address>:<bit> LVF<address>,<bit>	1-65536 Bit 0/1-15/16 0/1-Based Bit Addressing	Boolean, Word	Read/Write
Loop Control (C) Flags	LCF<address>	1-65535	DWord	Read/Write
Loop Control (C) Flag Bit Access**	LCF<address>.<bit> LCF<address>:<bit> LCF<address>,<bit>	1-65535 Bit 0/1-31/32 0/1-Based Bit Addressing	Boolean, DWord	Read/Write
Loop Ramp/Soak Status Flags	LRSF<address>	1-65536	Word	Read/Write
Loop Ramp/Soak Status Flag Bit Access***	LRSF<address>.<bit> LRSF<address>:<bit> LRSF<address>,<bit>	1-65536 Bit 0/1-15/16 0/1-Based Bit Addressing	Boolean, Word	Read/Write
Loop Error	LERR<address>	1-65535	Float	Read Only

Address Type	Format	Range	Data Types	Access
Loop Bias	LMX<address>	1-65535	Float	Read/Write
Loop High-High Alarm Limit	LHHA<address>	1-65535	Float	Read/Write
Loop Low-Low Alarm Limit	LLLA<address>	1-65535	Float	Read/Write
Loop Rate of Change Alarm Limit	LRCA<address>	1-65535	Float	Read/Write
Loop Setpoint High Limit	LSPH<address>	1-65535	Float	Read/Write
Loop Setpoint Low Limit	LSPL<address>	1-65535	Float	Read/Write
Loop Alarm Deadband	LADB<address>	1-65535	Float	Read/Write
Loop Raw High Alarm Limit	LHAR<address>	1-65536	Word	Read/Write
Loop Raw Low Alarm Limit	LLAR<address>	1-65536	Word	Read/Write
Loop Raw Process Variable	LPVR<address>	1-65536	Word	Read/Write
Loop Raw Orange Dev Alarm Limit	LODAR<address>	1-65536	Word	Read/Write
Loop Raw Yellow Dev Alarm Limit	LYDAR<address>	1-65536	Word	Read/Write
Loop Raw Output	LMNR<address>	1-65536	Word	Read/Write
Loop Raw Setpoint	LSPR<address>	1-65536	Word	Read/Write
Loop Raw Error	LERRR<address>	1-65536	Word	Read Only
Loop Raw High-High Alarm Limit	LHHAR<address>	1-65536	Word	Read/Write
Loop Raw Low-Low Alarm Limit	LLLAR<address>	1-65536	Word	Read/Write
Loop Raw Alarm Deadband	LADBR<address>	1-65536	Word	Read/Write
Loop Raw Bias	LMXR<address>	1-65536	Word	Read/Write
Loop Raw Setpoint Low Limit	LSPLR<address>	1-65536	Word	Read/Write
Loop Raw Setpoint High Limit	LSPHR<address>	1-65536	Word	Read/Write
Loop C Flags - MSW	LCFH<address>	1-65536	Word	Read/Write
Loop C Flags - LSW	LCFL<address>	1-65536	Word	Read/Write
Loop Derivative Gain Limit Coef.	LKD<address>	1-65535	Float	Read/Write
Loop Ramp/Soak Step Number	LRSN<address>	1-65536	Word	Read/Write
Loop Alarm ACK Flags	LACK<address>	1-65536	Word	Read Only

*For more information, refer to [LVF Bit Definitions](#).

**For more information, refer to [LCF Bit Definitions](#).

***For more information, refer to [LRSF Bit Definitions](#).

Array Support

Non-Boolean addresses accept array notation. To view data as an array, append '[rows][cols]' to an address. For example, V500 [2][2], V100 [12].

Packed Task Code Protocol

The following address types and arrays are not supported under Packed Task Code Protocol. CAMP Protocol will be used instead.

Loop Control (C) Flags (LCF)
 Loop Raw High Alarm Limit (LHAR)
 Loop Raw Low Alarm Limit (LLAR)
 Loop Raw Process Variable (LPVR)
 Loop Raw Orange Deviation (LODAR)
 Loop Raw Yellow Deviation (LYDAR)
 Loop Raw Output (LMNR)
 Loop Raw Setpoint (LSPR)
 Loop Raw Error (LERRR)
 Loop Raw High-High Alarm Limit (LHHAR)
 Loop Raw Low-Low Alarm Limit (LLLAR)
 Loop Raw Alarm Deadband (LADBR)
 Loop Raw Bias (LMXR)
 Loop Raw Setpoint Low Limit (LSPLR)
 Loop Raw Setpoint High Limit (LSPHR)

LVF Bit Definitions

Loop Variable Flag Data Element Format

The server default settings are shown in **bold**.

MSB		LSB	
ABCD	EFGH	IJKL	MNOP

The LVF bit has the following format:

V/W, X/Y

V=0-based bit addressing. Bit 0 is MSB.

W=1-based bit addressing. Bit 1 is MSB (Simatic 505 documentation).

X=0-based bit addressing. Bit 0 is LSB.

Y=1-based bit addressing. Bit 1 is LSB.

Element	LVF bit	Description
A	0/1, 15/16	1=Go to manual mode*
B	1/2, 14/15	1=Go to auto mode*
C	2/3, 13/14	1=Go to cascade mode*
D	3/4, 12/13	D E=description** 0 0=Loop is in manual mode
E	4/5, 11/12	1 0=Loop is in auto mode 0 1=Loop is in cascade mode
F	5/6, 10/11	0=Error is positive 1=Error is negative
G	6/7, 9/10	1=PV is in high-high alarm
H	7/8, 8/9	1=PV is in high alarm
I	8/9, 7/8	1=PV is in low alarm

Element	LVF bit	Description
J	9/10, 6 /7	1=PV is in low-low alarm
K	10/11, 5 /6	1=PV is in yellow deviation alarm
L	11/12, 4 /5	1=PV is in orange deviation alarm
M	12/13, 3 /4	1=PV is in rate-of-change alarm
N	13/14, 2 /3	1=Broken transmitter alarm
O	14/15, 1 /2	1=Loop is overrunning
P	15/16, 0 /1	Spare: Set to 0

*Elements A, B and C are write-only triggers. Write 1 to set the mode. The element will always show a value of 0 (zero).

**Elements D and E will indicate the mode that the loop is in. These elements are read only.

● **Note:** Elements F through P are read only and indicate the error and alarm state that the loop is in.

LCF Bit Definitions

Loop Control Flag Data Element Format

The server default settings are shown in **bold**.

MSB				LSB			
ABCD	EFGH	IJKL	MNOP	QRST	UVWX	YZab	cdef

The LCF bit has the following format:

V/W, X/Y

V=0-based bit addressing. Bit 0 is MSB.

W=1-based bit addressing. Bit 1 is MSB (Simatic 505 documentation).

X=0-based bit addressing. Bit 0 is LSB.

Y=1-based bit addressing. Bit 1 is LSB.

Element	LCF bit	Description
A	0/1, 31 /32	0=PV scale 0% offset 1=PV scale 20% offset - only valid if PV is unipolar. Refer to Element U.
B	1/2, 30 /31	1=Take square root of PV
C	2/3, 29 /30	1=Monitor HIGH/LOW alarms
D	3/4 28 /29	1=Monitor HIGH-HIGH/LOW-LOW alarms
E	4/5, 27 /28	1=Monitor yellow/orange deviation alarm
F	5/6, 26 /27	1=Monitor rate-of-change alarm
G	6/7, 25 /26	1=Monitor broken transmitter alarm
H	7/8, 24 /25	PID algorithm type 0=Position algorithm 1=Velocity algorithm
I	8/9, 23 /24	0=Direct acting 1=Reverse acting
J	9/10, 22 /23	1=Control based on error squared

Element	LCF bit	Description
K	10/11, 21/22	1=Control based on error deadband
L	11/12, 20/21	1=Auto-mode lock
M	12/13, 19/20	1=Cascade-mode lock
N	13/14, 18/19	1=Setpoint lock
O	14/15, 17/18	0=Output scale 0% offset 1=Output scale 20% offset - only valid if output is unipolar. Refer to Element T.
P	15/16, 16/17	<i>P Q</i> 0 1=No special function 1 0=Special function on the process variable
Q	16/17, 15/16	0 1=Special function on the setpoint 1 1=Special function on the output
R	17/18, 14/15	1=Freeze bias when output is out of range
S	18/19, 13/14	1=Ramp/Soak on the setpoint
T	19/20, 12/13	0=Output is unipolar 1=Output is bipolar
U	20/21, 11/12	0=PV is unipolar 1=PV is bipolar
V	21/22, 10/11	1=Perform derivative gain limiting
W	22/23, 9/10	Contains SF program number (if an SF program is scheduled to be called)
X	23/24, 8/9	Contains SF program number (if an SF program is scheduled to be called)
Y	24/25, 7/8	Contains SF program number (if an SF program is scheduled to be called)
Z	25/26, 6/7	Contains SF program number (if an SF program is scheduled to be called)
a	26/27, 5/6	Contains SF program number (if an SF program is scheduled to be called)
b	27/28, 4/5	Contains SF program number (if an SF program is scheduled to be called)
c	28/29, 3.4	Contains SF program number (if an SF program is scheduled to be called)
d	29/30, 2/3	Contains SF program number (if an SF program is scheduled to be called)
e	30/31, 1/2	Contains SF program number (if an SF program is scheduled to be called)
f	31/32, 0/1	Contains SF program number (if an SF program is scheduled to be called)

● **Note:** If the bit is set to 1, the option is enabled.

LRSF Bit Definitions

Ramp / Soak Status Data Element Format

The server default settings are shown in **bold**.

MSB		LSB	
ABCD	EFGH	IJKL	MNOP

The LRSF bit has the following format:

V/W, X/Y

V=0-based bit addressing. Bit 0 is MSB.

W=1-based bit addressing. Bit 1 is MSB (Simatic 505 documentation).

X=0-based bit addressing. Bit 0 is LSB.

Y=1-based bit addressing. Bit 1 is LSB.

Element	LRSF bit	Description
A	0/1, 15/16	1=Restart at the first step. To restart, toggle bit off, on, then off again. The restart occurs on the trailing edge of a square wave.
B	1/2, 14/15	1=Hold at the current step. To hold, set bit on.
C	2/3, 13/14	1=Jog to next step. To jog, set bit on. Jog occurs on the rising edge of a square wave.
D	3/4, 12/13	1=Finish. Indicates ramp/soak is completed.
E	4/5, 11/12	1=Wait. This bit is set during a soak period when the PV is not within a specified deviation from the SP. The loop holds the soak timer when bit 5 is set.
F	5/6, 10/11	1=Hold in progress at current step
G	6/7, 9/10	Unused (always returned as 0)
H	7/8, 8/9	Unused (always returned as 0)
I	8/9, 7/8	Ramp/soak step number currently executing
J	9/10, 6/7	Ramp/soak step number currently executing
K	10/11, 5/6	Ramp/soak step number currently executing
L	11/12, 4/5	Ramp/soak step number currently executing
M	12/13, 3/4	Ramp/soak step number currently executing
N	13/14, 2/3	Ramp/soak step number currently executing
O	14/15, 1/2	Ramp/soak step number currently executing
P	15/16, 0/1	Ramp/soak step number currently executing

Find Forced Addressing

Each address type only allows the one data type stated. No address type has a range.

Address Type	Format	Range	Data Types	Access
Find Forced Discrete Starting at X address	FFX	N/A	String	Read Only
Find Forced Discrete Starting at Y address	FFY	N/A	String	Read Only
Find Forced Discrete Starting at C address	FFC	N/A	String	Read Only
Find Forced Word Starting at WX address	FFWX	N/A	String	Read Only
Find Forced Word Starting at WY address	FFWY	N/A	String	Read Only
Find Forced Discrete / Word Starting address	FFSTART	N/A	DWord	Read/Write

Notes:

1. FFSTART is a driver internal tag (one per device) that is initialized to 1 on server startup. It has a write range of 1->65536 and a write of values outside of this range will fail with an error message.
2. If the starting address value in FFSTART is greater than the range for the Find Forced type issued, then the read will fail with an "Address out of Range" error (Task Code error '02') and the quality of the tag will be set to "Bad". For example, if FFSTART was set to a value of 65536 and a read of "FFC" was issued, the error generated would look similar to the following due to C memory in the PLC only being configured for maximum value of 32768: "Device 'Channel1.Device1' detected a Task Code error '02' (Tag 'ffc', Size '256')."

Usage

1. Perform a write to FFSTART with the value of the starting address to be used for the Find Forced type in Step 2.

Caution: Make sure that the value written is within the configured range for the type.

2. Perform a read using the Find Forced type selected. The read issues a command to the PLC asking it to perform a search for any Forced discretets (C, X/Y) or words (WX/WY).

Find Forced Search Algorithm

Using the specific address provided, the first forced address beginning with or following the starting address is output. The search will continue until it completes. A search is completed by one of the following: (1) the search proceeds through all locations in a circular manner and arrives back at the specified starting address or (2) enough addresses are found to fill the output buffer. The search will cycle through all address types (C then X/Y for discretets, WX/WY for words) for the command given.

If the search responds with the maximum number of addresses, then another request, beginning with the address following the last forced address returned, must be issued to continue the search. This must be repeated until the original starting address is reached to produce the complete list if a large number of addresses are forced.

Find Forced Search Notes

1. X/Y points reside in the same memory space (i.e. X1=Y1, X2=Y2, etc). The PLC will preferentially express X/Y points using Y addresses unless the search is explicitly started using an X address. Using FFX versus FFY lets users choose whether to have the results returned using an "X:address" format or a "Y:address" format.
2. WX/WY words reside in the same memory space (i.e. WX1=WY1, WX2=WY2, etc). The PLC will preferentially express WX/WY words using WY addresses unless the search is explicitly started using a WX address. Using FFWX versus FFWY lets users choose whether to have the results returned using an "WX:address" format or a "WY:address" format.

Examples

1. Write a value of 600 to a tag named 'ffstart', with an address of FFSTART.
2. Read a tag named 'ffc', with an address of FFC. Value returned in data type of string:
"<Start Address 00600>C:00600,C:00601,Y:00001,Y:01024,C:00001,C:00002"

This example illustrates the algorithm by which the Find Forced search is performed. The search was started at address C:00600 and it found two discretes forced at addresses C:00600,C:00601. It then proceeded to search X/Y discretes where it found Y:00001,Y:01024 forced. Next, it looped back around to the start of C discretes and found C:00001,C:00002 forced. Finally, it ended its search at C:00599 without finding any further forced discretes.

Output Formats

1. None (No Forced addresses found).
2. <Start Address SSSSS>Type1:Address1... up to ... Type15:Address15

where

SSSSS: value of FFSTART

Type: one of: C, X, Y, WX, WY

Address: fixed at five characters (00001 -> 65536)

● Notes:

1. A minimum of 1 address is returned.
2. A maximum of 15 addresses are returned if each returned address uses a one word format.
3. If an address consumes two words (due to the address not being within the first page), then the maximum output will be reduced by one for each two-word address. Users can determine if an address will consume one word or two by using the following:

C - Addresses

1 through 512 = one word

Addresses 513 through 65536 = two words

X,Y,WX,WY - Addresses

1 through 1024 = one word

Addresses 1025 through 65536 = two words

4. A maximum of seven addresses are returned if each returned address consumes two words.
5. The final output is independent of the address being returned in a one word or two word format.

6. The maximum string length is internally set to 256.

Error Descriptions

The following messages may be generated. Click on the link for a description of the message.

- [Address <address> is out of range for the specified device or register.](#)
- [Array size is out of range for address <address>.](#)
- [Array support is not available for the specified address: <address>.](#)
- [Data type <type> is not valid for device address <address>.](#)
- [Device address <address> contains a syntax error.](#)
- [Device address <address> is read only.](#)
- [Device <device name> cannot execute a read request \(<address>, <size>\).](#)
- [Device <device name> cannot execute a write request \(<address>, <size>\).](#)
- [Device <device name> detected a NITP protocol error \(tag <address>, size <size>\).](#)
- [Device <device name> detected a Task Code error <error> \(tag <address>, size <size>\).](#)
- [Device <device name> input queue is full. The module is receiving requests faster than it can process requests.](#)
- [Device <device name> is not responding.](#)
- [Device <device name> responded with Extended error <error> \(tag <address>, size <size>\).](#)
- [Device <device name>, write value not in range 1-->65536. \(Tag 'FFSTART'\).](#)
- [Missing address.](#)
- [Unable to write to <address> on device <device name>.](#)
- [Winsock initialization failed \(OS error = n\).](#)
- [Winsock V1.1 or higher must be installed to use the Simatic / TI 505 Ethernet device driver.](#)

See Also:

[Task Error Codes](#)

Address <address> is out of range for the specified device or register.

Error Type:

Warning

Possible Cause:

A tag address that has been specified dynamically references a location that is beyond the range of supported locations for the device.

Solution:

Verify the address is correct; if it is not, re-enter it in the client application.

Array size is out of range for address <address>.

Error Type:

Warning

Possible Cause:

A tag address that has been specified dynamically is requesting an array size that is too large for the address type or block size of the driver.

Solution:

Re-enter the address in the client application to specify a smaller value for the array or a different starting point.

Array Support is not available for the specified address: <address>.

Error Type:

Warning

Possible Cause:

A tag address that has been specified dynamically contains an array reference for an address type that doesn't support arrays.

Solution:

Re-enter the address in the client application to remove the array reference or correct the address type.

Data type <type> is not valid for device address <address>.

Error Type:

Warning

Possible Cause:

A tag address that has been specified dynamically has been assigned an invalid data type.

Solution:

Modify the requested data type in the client application.

Device address <address> contains a syntax error.

Error Type:

Warning

Possible Cause:

A tag address that has been specified dynamically contains one or more invalid characters.

Solution:

Re-enter the address in the client application.

Device address <address> is read only.

Error Type:

Warning

Possible Cause:

A tag address that has been specified dynamically has a requested access mode that is not compatible with what the device supports for that address.

Solution:

Change the access mode in the client application.

Device <device name> cannot execute a read request (<address>, <size>).

Error Type:

Serious

Possible Cause:

The device is unable to return the amount of read data requested in one request.

Solution:

Adjust the requested block size on the device so that the driver makes smaller requests.

Device <device name> cannot execute a write request (<address>, <size>).

Error Type:

Serious

Possible Cause:

The device is unable to receive the amount of write data sent in one request.

Solution:

Adjust the array size on the address so that a smaller amount of data is sent to the device in one transaction.

Device <device name> detected a NITP protocol error (tag <address>, size <size>).

Error Type:

Serious

Possible Cause:

This error may occur when sending Packed Task Code messages. The device is experiencing network errors.

Solution:

Check network connections.

Device <device name> detected a Task Code error <error> (tag <address>, size <size>).

Error Type:

Serious

Possible Cause:

This error may occur when sending Packed Task Code messages.

The device is experiencing network errors or PLC encountered an error when processing a task code.

Solution:

1. Check network connections.
2. Refer to the specific error code.

See Also:[Task Error Codes](#)

Device <device name> input queue is full. The module is receiving requests faster than it can process requests.

Error Type:

Serious

Possible Cause:

The device is handling requests from more than one PC at a time.

Solution:

Using the device programming software, make sure that the "task codes per scan time" property is set to 8. Adjusting the scan time may also improve device performance. It is recommended that users set the scan time to Variable. For more information on adjusting these properties, refer to the device's documentation.

Device <device name> is not responding.

Error Type:

Serious

Possible Cause:

1. The connection between the device and the host PC is broken.
2. The IP address assigned to the device is incorrect.
3. The response from the device took longer to receive than the amount of time specified in the "Request Timeout" device property.

Solution:

1. Verify the cabling between the PC and the PLC device.
2. Verify that the IP address given to the named device matches that of the actual device.
3. Increase the Request Timeout property so that the entire response can be handled.

Device <device name> responded with Extended error <error> (tag <address>, size <size>).

Error Type:

Informational

Possible Cause:

The device is unable to receive the amount of write data sent in one request.

Note:

This error is used for extended error information by some error responses.

• **See Also:** *Device <device name> cannot execute a write request (<address>, <size>).*

Device <device name>, write value not in range 1-->65536. (Tag 'FFSTART').

Error Type:

Warning

Possible Cause:

Value written outside of range specified.

Solution:

Write a value in the range of 1-65536.

Missing address.

Error Type:

Warning

Possible Cause:

A tag address that has been specified dynamically has no length.

Solution:

Re-enter the address in the client application.

Unable to write to <address> on device <device name>.

Error Type:

Serious

Possible Cause:

1. The connection between the device and the host PC is broken.
2. The IP address assigned to the device is incorrect.

Solution:

1. Verify the cabling between the PC and the PLC device.
2. Verify that the IP address given to the named device matches that of the actual device.

Winsock initialization failed (OS error = n).

Error Type:

Fatal

OS Error	Possible Solution
10091	Indicates that the underlying network subsystem is not ready for network communication. Wait a

OS Error	Possible Solution
	few seconds and restart the driver.
10067	Limit on the number of tasks supported by the Windows Sockets implementation has been reached. Close one or more applications that may be using Winsock and restart the driver.

Winsock V1.1 or higher must be installed to use the Simatic / TI 505 Ethernet Driver.

Error Type:

Fatal

Possible Cause:

The version number of the Winsock DLL found on the system is less than 1.1.

Solution:

Upgrade Winsock to version 1.1 or higher.

Task Code Error Codes

Code	Description
02	Address out of range (other than ladder logic).
03	Requested data not found.
04	Illegal task code request (such as "Task Code not supported").
05	Request exceeds program memory size (ladder logic).
07	Fatal error detected.
09	Incorrect amount of data sent with request.
0C	Attempted write operation did not verify.
0D	Illegal number of ASCII characters received.
0E	Illegal write to program memory (Non Volatile).
11	Invalid data sent with the command.
16	Attempted write to a Protected Variable (such as TCC and TCP).
17	No response from PLC (such as, "Single Scan not performed").
18	Requested memory size exceeds total available memory.
19	Requested memory size is not a multiple of block allocation size.
1A	Requested memory size is less than minimum defined value.
1B	Requested memory size is larger than maximum defined value.
1C	PLC busy - cannot complete the requested operation.
3F	Bus error detected.
40	Operating system error detected.
4A	Attempt to access an integer only variable as a real.
4B	Attempt to access a real. Only value as an integer.
4C	Task code buffer overflow. Too much data requested.
4E	Attempt to write a read-only variable.
4F	Invalid variable type for this operation.
50	Task code request buffer too large. PLC internal error.

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